Subject: RE: S3374: Controls questions

From: Douglas Smith < Douglas. Smith@FMB-Oxford.com>

Date: 9/11/2017 2:56 AM

To: Eric Dufresne <dufresne@anl.gov>

CC: Richard Green < Richard.Green@FMB-Oxford.com >, Jonathan Randall < Jonathan.Randall@FMB-

Oxford.com>

Good morning Eric,

Sorry for the delayed reply I have been out of the office. Generally we use ZMX+ Phytron driver cards set for 1/20 step for our tests, we can go higher depending on the resolution of the system (our rule is >3 encoder counts per motor step for a stable closed loop system).

Motor speeds can vary but we use 2cts/msec as a starting point, acceleration for slits isn't too important so try 20msec also as a starting point.

Hope this helps, if you requires anything further please let me know.

Regards, Doug.

Electrical project Engineer
FMB Oxford LTD
Head Office
Unit 1 Ferry Mills
Osney Mead
Oxford OX2 ØES
United Kingdom

Tel: +44 (0)1865 320334 Fax: +44 (0)1865 320301

Email: douglas.smith@fmb-oxford.com

Web: www.fmb-oxford.com

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